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## Buckling of XL monopiles during installation

THELL 4

Ramning af monopæle og maskinudvikling

Ulrik Muurholm Hansen

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- > Name: Ulrik Muurholm Hansen
- Education: Master of Science in Civil Engineering, Technical University of Denmark
- Company: COWI 1703 Marine & Foundation Engineering department (since 2011)
- > Title: Structural designer
- Reference projects: HR 3 & KF AC Transformer Platforms, DanTysk OWF Detailed Design, Formosa 1 OWF.

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Introduction Buckling during installation Results and conclusions

## Introduction

#### > About WMR

- > 11 km off Yorkshire coast covering 35  $\rm km^2$
- > 35 SWT-6.0-154 (Siemens) turbines (210 MW)
- > MP foundations with OD 6.5 m (D/t=120)
- > Water depth 10-25m
- Completion of foundation installation by GeoSea 25-May-2014.



## Introduction

#### > About BBW02

- > 8 km from shore in Liverpool Bay covering 40 km<sup>2</sup>
- > Owner and developer is DONG Energy
- > 32 V164-8.0 MW (Vestas) turbines (256 MW)
- > MP foundations with OD 7.097m
- > Water depth 4-17 m.



## Introduction (cont.)

- > Project describtion
  - > DONG asked COWI to investigate whether local shell buckling of MPs during installation (impact driving) was an issue
  - > Offshore guideline limitations:
    - > NORSOK N004: D/t<120
    - > ISO19902: D/t≤120
    - > EN 1993-1-6: 20≤r/t≤5000
    - > (LBA, MNA, GNIA, GMNIA)





(b) STATICALLY BUCKLED





## Buckling during installation The physics of pile driving





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## Buckling during installation

### The physics of pile driving



# Buckling during installation

GRLWEAP – Stress Wave Propagation Modelling

#### > GRLWEAP output

- > Normal stress in pile
- > Radial soil pressure inside/outside pile
- > 35 locations, 100 segment, approx. 30 driving depth for two soil models.







# Buckling during installation (cont.)

### Shell buckling verification

- Obtain normal force and cross-sectional parameters from GRLWEAP
- > Determine stresses near cable entries
- Account for imperfections (hammer misalignment and MP out-of-verticality)
- Determined shell design stresses (axial, hoop, shear)
- Apply EN1993-1-6 for buckling verification
- Determine capacity near cable entries LBA method
- > Determine UR in relation to shell buckling
- > Report results.





## Buckling during installation (cont.) Detailed Dynamic FEA Model

- > Non-linear geometry
- Elastic-perfectly-plastic material behaviour for structural steel
- Non-linear boundary conditions (soil) including viscous damping
- Imperfections explicitly modelled when applying GMNIA method.



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### Results and conclusions WMR results

>  $UR_x$ ,  $UR_{\theta}$ ,  $UR_{comb.}$  for 35 locations for approx. 30 driving depths for 100 pile segments



## Results and conclusions (cont.) WMR Results

- For all 35 MP locations the local shell buckling utilisation ratio was found to be below 1.0 for both upper- and lower bound soil conditions. The quasi-static EN1993-1-6 approach was applied (LBA, MNA etc.)
- > For the most critical MP location a highly detailed dynamic FEA was carried out
- For large imperfections local yielding at dents and dimples may occur. Possible mitigation measures are, stricter requirements to fabrication tolerances, lowering of the D/t ratio for specific MP cans, take advantage of higher yield strength for rapid loading, reduce hammer impact force
- > The final MP design is unknown to COWI.





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- For one MP position a parameter study on, steel grade, fabrication tolerances, and hammer sizes was carried out
- Higher steel grade i.e. S420 instead of S355 is less beneficial compared to stricter requirements to fabrication tolerances
- The maximum allowable D/t ratio is highly dependent on the radial soil stresses which generate hoop stresses in the MP
- > Dependant on the choice of hydrohammer and radial soil stresses the D/t ratio for the specific site can be increased to 140.





- D/t ratios for MPs are still increasing and at some point it might not be possible to install MPs by impact driving due to large slenderness of the structures
- More advanced methods may be utilized in order to verify the shell buckling capacity e.g. dynamic GMNIA taken into account rapid loading effects
- Increasing D/t ratios should go hand in hand with lower fabrication tolerances.

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